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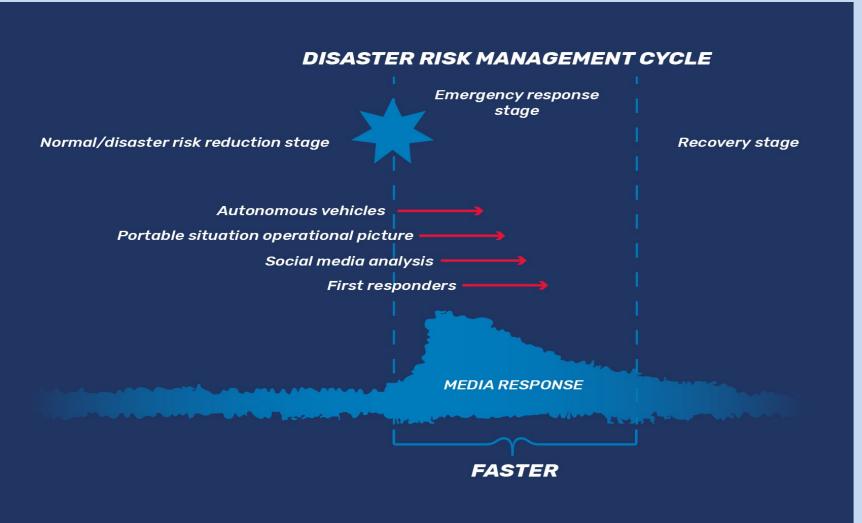
# #EPOS033 FASTER project new technologies evaluation in a simulated earthquake pilot in Madrid during the covid19 pandemic.

Julio RUIZ PALOMINO, Ana Maria CINTORA SANZ, Soledad GOMEZ DE LA OLIVA, Ana DIAZ HERRERO, Oscar CARRILLO FERNANDEZ, Francisco Jose CARRILLO ZAMORA. **SUMMA112 Madrid, Spain** 



## Background:

• FASTER¹ (First responder Advanced technologies for Safe and efficienT Emergency Response) is a H2020 funded² project that address the protection and capabilities of first responders in hazardous environments and disasters. We performed a simulated earthquake pilot exercise to test different tools that can improve the response despite the COVID 19 pandemic in Escuela Nacional de Protección Civil, in Madrid, taken in account the disaster risk management cycle and INSARAG Guidelines³.





**Graphic1:** : Disaster Risk Management Cycle

Picture 1: Simulated Scenario

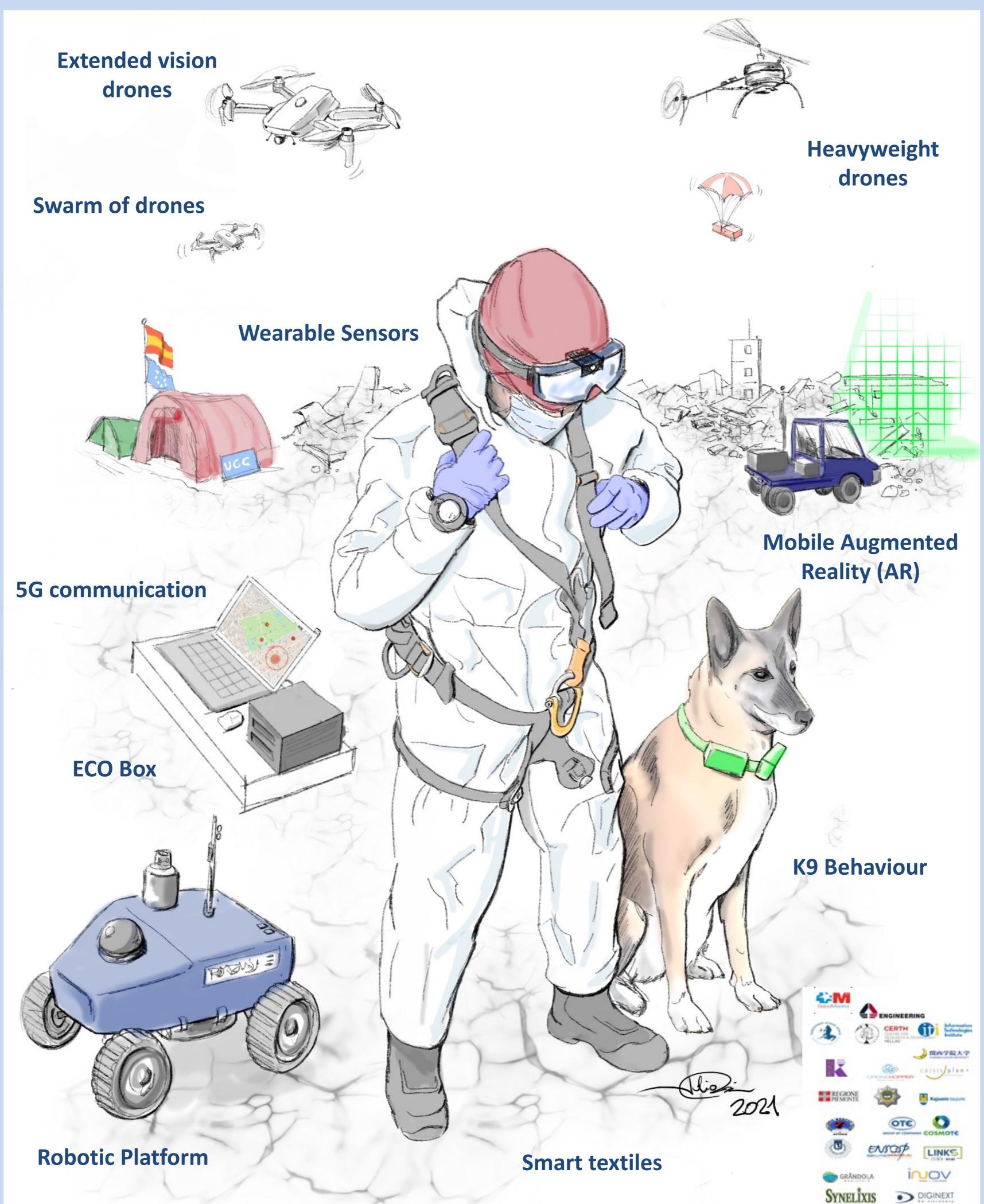
## Methods:

Our aim was to test and prove the FASTER tools in a realistic and complex environment, gathering user feedback related to the acceptability, usability, functionality, and efficiency. Assessment of the innovated COVID19 protocol <sup>3</sup>, developed for this situation, to work safely in a natural disaster during this pandemic was also a priority. We designed a simulated scenario within a limited area of collapsed buildings, including several victims needed to be rescued in an urban zone.

USAR ERICAM and Madrid Local Police first responders' teams were deployed during a 12-hour drill, working in various places while observers monitored that all security special measures taken for Covid-19 pandemic were met. The entire exercise is recorded from the air with drones of Madrid Municipal Police, to make a professional video that collects all the Pilot's sequences that we could later review. FASTER tools, including drones, autonomous vehicles, canine collars and portable command control services were tested by the researchers through recording, notes and improvement lists.



#### Keywords: Disaster, Tools Evaluation, Covid19, Pilot, USAR Rescue



Picture 2: Iconographie of FASTER' Tools tested in Madrid Pilot<sup>4</sup>

#### REFERENCES:

1.https://www.faster-project.eu/

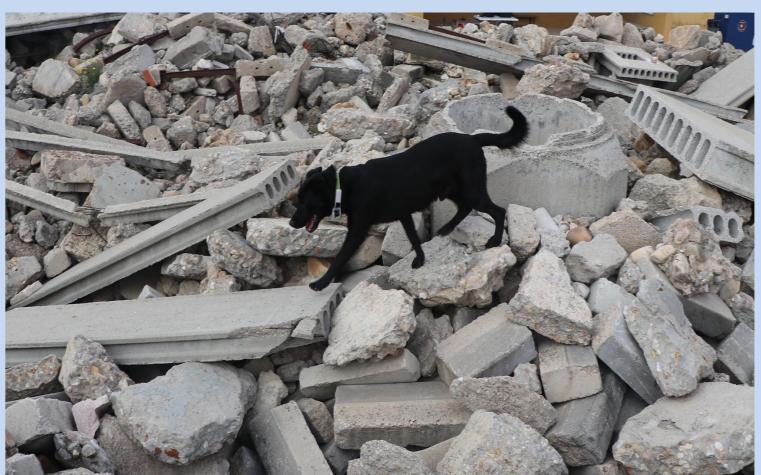
2.https://cordis.europa.eu/project/id/833507

3. <a href="https://www.insarag.org/wp-content/uploads/2021/03/MWG-Covid-19-USAR-Response-Technical-Guidance-Note-Final.pdf">https://www.insarag.org/wp-content/uploads/2021/03/MWG-Covid-19-USAR-Response-Technical-Guidance-Note-Final.pdf</a>

4 https://www.faster-project.eu/madrid-pilot-3

### **Results:**

Initial evaluation and sectorization of the critical zone with drones provided updates regarding casualties, structural damage and entry points. Localization and extraction of four victims could be possible sooner with thermal cameras and 3D mapping, compared to previous scenarios without these tools. The continuous evaluation of K9 members with wearable devices was achieved for the first time in our team. Team operations followed hygiene and social distancing standards without interfering in the main mission. FASTER tools have been testing their acceptability, functionality and effectiveness, taking in account with this key-performance indicators.





Picture 3: K9 precise location

Picture 4: Drones monitoring devices

## **Conclusion & Discussion:**

The tested devices optimized the assessment and coordination between commanders and intervention teams, improving prioritization, and reducing coordination, logistics and assistance times compared to previous exercises made without the tools. The use of ground robots in the initial ASRs reduces the need for in vivo approach of the professionals, reducing the exposure of professionals to biological risk.

The exercise allowed gathering of user feedback for incorporation into future tool development that could improve disaster response.

The **Monitoring of health and social distancing** during the scenario were performed with safety and it **can be applied in a real USAR Rescue mission** during the Covid19 pandemic.

As a point of improvement we recommend accompanying visual stimuli (lights on the ground and/or beacons) that make it easy to visualise the permitted and prohibited zones, as well as the flow of movement. The marking of dirty and clean circuits was developed in a successful way